**Exemple de code pour envoyer une information UART sur dynamixel:**

<https://raspberrypi.stackexchange.com/questions/105589/raspberry-pi-3-b-buster-cant-control-dynamixel-ax-12a-with-raspberry-pi-3-b>

**Dynamixel AX12 and Raspberry PI et 74LS41N :**

<http://www.oppedijk.com/robotics/control-dynamixel-with-raspberrypi>

**Ma dernière erreur :**

pi@raspberrypi:~/Documents/Dynamixel $ sudo python test.py

test.py:6: RuntimeWarning: This channel is already in use, continuing anyway. Use GPIO.setwarnings(False) to disable warnings.

GPIO.setup(18, GPIO.OUT)

GPIO HIGH

^[[A^[[C^X^CTraceback (most recent call last):

File "test.py", line 14, in <module>

port.write(bytearray.fromhex("FF FF 00 05 03 20 FF 00 D8"))

File "/usr/lib/python2.7/dist-packages/serial/serialposix.py", line 556, in write

abort, ready, \_ = select.select([self.pipe\_abort\_write\_r], [self.fd], [], None)